

# The Time Hierarchy Theorem

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## 1 Statement and Proof

In this lecture we use the **self** programming construct along with the Turing machine model of computation to prove the Time Hierarchy Theorem (see Chapter 9 of Sipser’s Theory of Computation).

**Definition 1.1.** Let function  $t : \mathcal{N} \rightarrow \mathcal{N}$  satisfy  $t(n) \geq n \log n$  for all  $n \geq 0$ . Then  $t$  is said to be **time constructible** iff there is a transducer TM that, on input  $1^n$  is able to output the binary representation of  $t(n)$  in at most  $O(t(n))$  steps.

Note that the (log, polynomial, and exponential) functions that we tend to care most about are all time constructible (exercise!).

**Theorem 1.2.** (Time Hierarchy Theorem) If  $t(n)$  is time constructible, then there is a decision problem that can be decided in  $O(t(n))$  steps, but cannot be decided in  $o(t(n)/\log t(n))$  steps.

**Proof.** Consider the decision problem  $L$  for which a positive instance is a pair  $\langle M, w \rangle$ , where  $M$  is the encoding of a deterministic Turing machine,  $w \in \Sigma^*$  is an input word for  $M$ , and  $M$  accepts  $w$  within  $t(n)/\log t(n)$  steps. Then  $L$  can be decided in  $O(t(n))$  steps via a TM  $\hat{M}$  which, on input  $\langle M, w \rangle$  simulates the computation of  $M(w)$  for  $t(n)/\log t(n)$  steps. It does this by interleaving the work tape with

1. cells  $c_0, c_1, c_2, \dots$  that represent the actual computation  $M(w)$  along with
2.  $O(\log t(n))$ -lengthed blocks of cells  $B_0, B_1, B_2, \dots$  each of which stores a copy of  $M$  along with a binary number of length  $\lfloor \log t(n) \rfloor$  that serves as a “timer” for keeping track of the remaining number of steps to perform in the simulation.

This interleaving process is necessary, since  $\hat{M}$  can only afford a simulation overhead of  $O(\log t(n))$  steps per simulation step and thus must always be within a constant number of steps from  $M$  and

the binary “timer”. Therefore  $\hat{M}$  can decide instance  $\langle M, w \rangle$  in

$$O(\log(t(n)) \cdot t(n) / \log(t(n))) = O(t(n))$$

steps as desired. For the sake of concreteness, let  $c_1 > 0$  be a constant so that  $\hat{M}$  runs in at most  $c_1 \cdot t(n)$  number of steps, where  $n = |\langle M, w \rangle|$ .

Now suppose  $L$  is *also* decidable by TM  $M'$  in  $s(n) = o(t(n) / \log t(n))$  steps, meaning that

$$L = L(\hat{M}) = L(M').$$

Consider the following informal program for some TM  $Q$ .

Input  $w$ .

Simulate  $M'$  on input  $\langle \mathbf{self}, w \rangle$ .

Return  $1 - M'(\langle \mathbf{self}, w \rangle)$ .

To finish the proof, we make the following points.

1. Unlike  $\hat{M}$ 's simulation of  $M(w)$  which requires  $\hat{M}$  to keep track of the number of simulation steps,  $Q$  does not care about the length of the simulation of  $M'(\langle \mathbf{self}, w \rangle)$ , and follows it all the way to its completion. Because of this  $Q$  completes its simulation in no more than  $c_2 \cdot s(n)$  steps, where  $c_2 > 0$  is some constant and  $n = |\langle \mathbf{self}, w \rangle|$ .
2. Since  $s(n) = o(t(n) / \log t(n))$ , by definition this means that

$$\lim_{n \rightarrow \infty} \frac{c_2 \cdot s(n)}{c_1 \cdot t(n)} = 0.$$

Thus, for  $n$  sufficiently large,  $c_2 \cdot s(n) < c_1 \cdot t(n)$ .

3. Now let  $w$  be a word for which  $n = |w|$  is so large that  $c_2 \cdot s(n) < c_1 \cdot t(n)$ . Then  $Q$  will complete its simulation of  $M'(\langle \mathbf{self}, w \rangle)$  in fewer than  $c_1 \cdot t(n)$  steps, which means

$$\hat{M}(\langle Q, w \rangle) = Q(w) = 1 - M'(\langle Q, w \rangle),$$

where the second equality comes from the fact that the computation  $Q(w)$  involves simulating  $M'(\langle Q, w \rangle)$  and returning the opposite result of that simulation. Thus,  $\hat{M}$  and  $M'$  return different values on input  $\langle Q, w \rangle$ , which contradicts the assumption that both machines accept the same language. Therefore,  $M'$  does not exist which proves the theorem.  $\square$

## 2 The Complexity Class EXPTIME

Complexity class EXPTIME is defined as the set of all decision problems  $L$  that can be decided in  $O(2^{p(|x|)})$  steps for each instance  $x$  of  $L$ , where  $p$  is some polynomial.

**Corollary 2.1.** Class P is a proper subset of EXPTIME.

**Proof.** Since  $\log 2^n = n$  and  $n^k = o(2^n/n)$  for all  $k \geq 0$ , it follows by the Time Hierarchy theorem that there is a decision problem  $L$  that requires  $O(2^n/n)$  steps, yet cannot be decided in a polynomial number of steps. Therefore,  $L \in \text{EXPTIME} - \text{P}$ .  $\square$

## 3 The Space Hierarchy Theorem

We now provide an analogous space hierarchy theorem whose proof is left as an exercise.

**Definition 3.1.** Let function  $s : \mathcal{N} \rightarrow \mathcal{N}$  satisfy  $s(n) = \Omega(\log n)$ . Then  $s$  is said to be **space constructible** iff there is a transducer TM that, on input  $1^n$  is able to output the binary representation of  $s(n)$  using at most  $O(s(n))$  space.

Note that the (log, polynomial, and exponential) functions that we tend to care most about are all space constructible (exercise!).

**Theorem 3.2.** (Space Hierarchy Theorem) If  $s(n)$  is space constructible, then there is a decision problem that can be decided in  $O(s(n))$  space, but cannot be decided in  $o(s(n))$  space.